

Scilab tutorial – satellite orbit around the earth



1. Express the physics problem

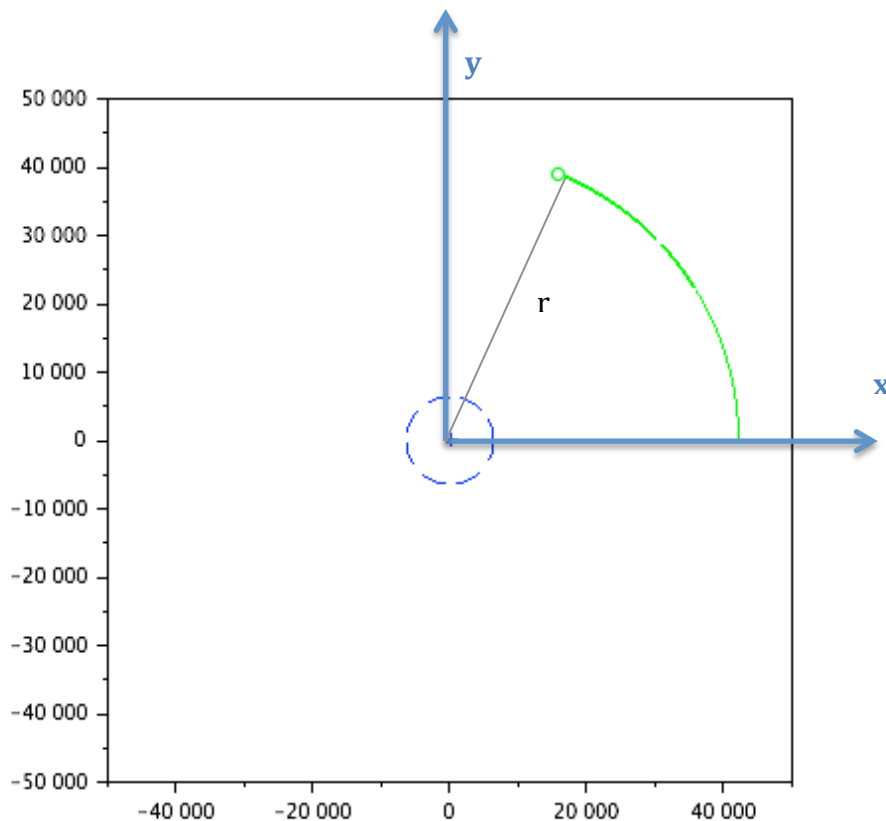
The problem is based on the universal law of gravitation:

$$\vec{F} = -G * \frac{m * M}{\|\vec{r}\|^2} * \frac{\vec{r}}{\|\vec{r}\|}$$

We write down Newton's third law of motion in an earth-centred referential:

$$m * \ddot{x} = -G * \frac{m * M}{(\sqrt{x^2 + y^2})^3} * x \quad (1)$$

$$m * \ddot{y} = -G * \frac{m * M}{(\sqrt{x^2 + y^2})^3} * y \quad (2)$$



Position of the satellite is at a distance $r [x; y]$
Earth mass centre is at $O [0; 0]$

Constants of the problem:

Gravitational constant $G = 6.67 \times 10^{-11} \text{ m}^3 \text{ kg}^{-1} \text{ s}^{-2}$

Mass of the earth $M = 5.98 \times 10^{24} \text{ kg}$

Radius of the Earth $r_{\text{earth}} = 6.38 \times 10^6 \text{ m}$

2. Translate your problem into Scilab

Scilab is a matrix-based language. Instead of expressing the system as set of 4 independent equations (along the x and y axis, for position and speed), we describe it as a single matrix equation, of dimension 4x4:

This method is a classical trick to switch from a second order scalar differential equation to a first order matrix differential equation.

$$\dot{u} = A \cdot u$$

$$\text{with } A = \begin{bmatrix} 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ c/r^3 & 0 & 0 & 0 \\ 0 & c/r^3 & 0 & 0 \end{bmatrix}, u = \begin{bmatrix} x \\ y \\ \dot{x} \\ \dot{y} \end{bmatrix}$$

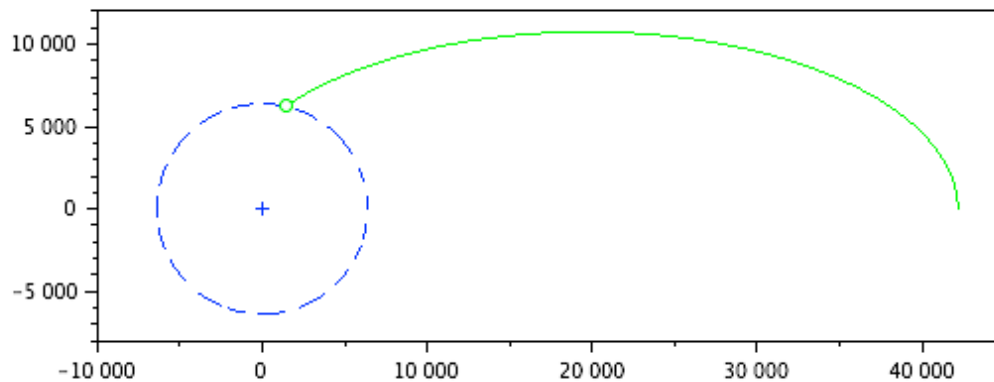
To simplify the equation, we define the variable $c = -G * M$

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Define the skeleton of the function:

```
function udot=f(t, u)
    G = 6.67D-11; //Gravitational constant
    M = 5.98D24; //Mass of the Earth
    c = -G * M;
    r_earth = 6.378E6; //radius of the Earth
    r = sqrt(u(1)^2 + u(2)^2);
    // Write the relationhsip between udot and u
    if r < r_earth then
        udot = [0 0 0 0]';
    else
        A = [[0 0 1 0];
             [0 0 0 1];
             [c/r^3 0 0 0];
             [0 c/r^3 0 0]];
        udot = A*u;
    end
endfunction
```

The condition defined by the distance r of the satellite with the centre of earth stops the simulation if it's colliding with earth's surface.



Try out the final script with the following initial conditions in speed and altitude:

```
geo_alt = 35784; // in kms
geo_speed = 1074; // in m/s
simulation_time = 24; // in hours
U = earthrotation(geo_alt, geo_speed, simulation_time);
```

3. Compute the results and create a visual animation

With this function, we go to the core of the problem.

```
function U=earthrotation(altitude, v_init, hours)
// altitude given in km
// v_init is a vector [vx; vy] given in m/s
// hours is the number of hours for the simulation
r_earth = 6.378E6;
altitude = altitude * 1000;
U0 = [r_earth + altitude; 0; 0; v_init];
t = 0:10:(3600*hours); // simulation time, one point every 10 seconds
U = ode(U0, 0, t, f);

// Draw the earth in blue
angle = 0:0.01:2*%pi;
x_earth = 6378 * cos(angle);
y_earth = 6378 * sin(angle);
fig = scf();
a = gca();
a.isoview = "on";
plot(x_earth, y_earth, 'b--');
plot(0, 0, 'b+');
// Draw the trajectory computed
comet(U(1,:)/1000, U(2,:)/1000, "colors", 3);
endfunction
```

The resolution of the ordinary differential equation (ODE) is computed with the Scilab function [ode](#).

ode solves Ordinary Different Equations defined by:

$$\dot{y} = f(t, y)$$

where y is a real vector or matrix

The simplest call of ode is: $y = \text{ode}(y_0, t_0, t, f)$ where y_0 is the vector of initial conditions, t_0 is the initial time, t is the vector of times at which the solution y is computed and y is matrix of solution vectors $y = [y(t(1)), y(t(2)), \dots]$.

To go further in numerical analysis, find out more about the solvers:

[Ordinary Differential Equations with Scilab, WATS Lectures, Université de Saint-Louis, G. Sallet, 2004](#)

Complete script

```
//
// Scilab ( http://www.scilab.org/ ) - This file is part of Scilab
// Copyright (C) 2015-2015 - Scilab Enterprises - Pierre-Aimé Agnel
//
// This file must be used under the terms of the CeCILL.
// This source file is licensed as described in the file COPYING, which
// you should have received as part of this distribution. The terms
// are also available at
// http://www.cecill.info/licences/Licence_CeCILL_V2.1-en.txt
//

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    else
        A = [[0 0 1 0];
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//Earth Rotation at geostationnary orbit
geo_alt = 35784; // in kms
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simulation_time = 24; // in hours
U = earthrotation(geo_alt, geo_speed, simulation_time);

```